1.4 Eigenvalues and Eigenvectors of matrices

In general the transformation A of the vectors x leads to

$$
y = Ax \tag{1.20}
$$

where y is rotated against x and the lengths of both vectors differ. Now we are looking for special vectors v with

$$
Av = \lambda v = \lambda Ev \tag{1.21}
$$

These "Eigenvectors" only change their length, when the operator A is applied to them. Eq. (1.21) can be rewritten as

$$
(A - \lambda E)v = 0 \tag{1.22}
$$

This equations has only nontrivial solutions if

$$
\det(A - \lambda E) = 0 \tag{1.23}
$$

The zeros of this characteristic polynom are the Eigenvalues λ_i of the operator A. For each Eigenvalue λ_i we can calculate the Eigenvectors v_i by solving the equation

$$
(A - \lambda_i E)v_i = 0 \tag{1.24}
$$

Example:

The matrix $\begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix}$ has the characteristic polynom $\lambda^2 - 6\lambda + 8 = 0$ with its solutions $\lambda_1 = 2$ and $\lambda_2 = 4$. $\begin{pmatrix} 1 \end{pmatrix}$) and $\vec{v}_2 = \frac{1}{\sqrt{2}}$ $\begin{pmatrix} 1 \end{pmatrix}$.

The corresponding Eigenvectors are $\vec{v}_1 = \frac{1}{\sqrt{2}}$ 2 −1 2 1 The adjacent unitary transformation is therefore $U = \frac{1}{\sqrt{2}}$ \overline{c} $\begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$.

An illustrative example for an Eigenvalue problem you can find in the [math-script.](https://www.tf.uni-kiel.de/matwis/amat/math_for_ms/kap_1/backbone/r_su6.html)

Eigenvalues of linear Hermitian Operators are always real

Let A be a Hermitian operator with the Eigenfunction f_1 and the Eigenvalue a_1 ; it follows that

$$
a_1 \langle f_1 | f_1 \rangle = \langle f_1 | Af_1 \rangle = \langle Af_1 | f_1 \rangle = a_1^* \langle f_1 | f_1 \rangle \tag{1.25}
$$

thus a_1 is real.

Eigenvectors belonging to different Eigenvalues are orthogonal

Let A be a Hermitian operator with Eigenfunctions f_1 and f_2 . Let $a_1 \neq a_2$ be the corresponding Eigenvalues. We find

$$
a_2 \langle f_1 | f_2 \rangle = \langle f_1 | Af_2 \rangle = \langle Af_1 | f_2 \rangle = a_1^* \langle f_1 | f_2 \rangle \tag{1.26}
$$

Consequently

$$
(a_2 - a_1^*) \langle f_1 | f_2 \rangle = 0 \qquad ; \qquad (1.27)
$$

since $(a_2 - a_1^*) \neq 0$ we find that f_1 and f_2 are orthogonal.

Degenerated Eigenvalues

Let A be a Hermitian operator with the Eigenfunctions f_1 and f_2 . Let $a_1 = a_2 = a$ be the corresponding Eigenvalue, i.e.

$$
A|f_1\rangle = a|f_1\rangle
$$

$$
A|f_2\rangle = a|f_2\rangle
$$
 (1.28)

We find:

$$
A(x|f_1\rangle + y|f_2\rangle) = xa|f_1\rangle + ya|f_2\rangle = a(x|f_1\rangle + y|f_2\rangle) \tag{1.29}
$$

Thus degenerated Eigenfunctions form a sub vector space. This sub space is perpendicular to all other Eigenvectors. The orthonormalization procedure of Schmidt allows to find a set of orthogonal vectors of length 1 in this subspace.

Orthonormal base of vectors

The system of Eigenvectors for every Hermitian matrix can thus be transformed to a set of orthonormal vectors e_i , with represent a basis in the vector space:

$$
\langle e_i | e_j \rangle = \delta_{i,j} \tag{1.30}
$$

Each vector can be written as

$$
\langle a| = \sum_{i} \langle a|e_i \rangle \langle e_i| \tag{1.31}
$$

which is called the Closure-relation. The $a_i = \langle a | e_i \rangle$ are called the components of the vector for the basis e_i . In component representation the vector is just written as $\langle a| = (a_1, a_2, a_3, ..., a_n)$.

REMARK: Remember the Bra-, Ket- representation of vectors; for complex vectors the components have to be chosen complex conjugated when changing from Bra- to Ket- representation or vice versa.