# **1.4** Eigenvalues and Eigenvectors of matrices

In general the transformation A of the vectors x leads to

$$y = Ax \tag{1.20}$$

where y is rotated against x and the lengths of both vectors differ. Now we are looking for special vectors v with

$$Av = \lambda v = \lambda Ev \tag{1.21}$$

These "Eigenvectors" only change their length, when the operator A is applied to them. Eq. (1.21) can be rewritten as

$$(A - \lambda E)v = 0 \tag{1.22}$$

This equations has only nontrivial solutions if

$$\det(A - \lambda E) = 0 \tag{1.23}$$

The zeros of this characteristic polynom are the Eigenvalues  $\lambda_i$  of the operator A. For each Eigenvalue  $\lambda_i$  we can calculate the Eigenvectors  $v_i$  by solving the equation

$$(A - \lambda_i E)v_i = 0 \tag{1.24}$$

### Example:

The matrix  $\begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix}$  has the characteristic polynom  $\lambda^2 - 6\lambda + 8 = 0$  with its solutions  $\lambda_1 = 2$  and  $\lambda_2 = 4$ . The corresponding Eigenvectors are  $\vec{v}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  and  $\vec{v}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

The adjacent unitary transformation is therefore  $U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$ .

An illustrative example for an Eigenvalue problem you can find in the math-script.

## Eigenvalues of linear Hermitian Operators are always real

Let A be a Hermitian operator with the Eigenfunction  $f_1$  and the Eigenvalue  $a_1$ ; it follows that

$$a_1\langle f_1|f_1\rangle = \langle f_1|Af_1\rangle = \langle Af_1|f_1\rangle = a_1^*\langle f_1|f_1\rangle$$
(1.25)

thus  $a_1$  is real.

# Eigenvectors belonging to different Eigenvalues are orthogonal

Let A be a Hermitian operator with Eigenfunctions  $f_1$  and  $f_2$ . Let  $a_1 \neq a_2$  be the corresponding Eigenvalues. We find

$$a_2\langle f_1|f_2\rangle = \langle f_1|Af_2\rangle = \langle Af_1|f_2\rangle = a_1^*\langle f_1|f_2\rangle \tag{1.26}$$

Consequently

$$(a_2 - a_1^*)\langle f_1 | f_2 \rangle = 0$$
 ; (1.27)

since  $(a_2 - a_1^*) \neq 0$  we find that  $f_1$  and  $f_2$  are orthogonal.

### Degenerated Eigenvalues

Let A be a Hermitian operator with the Eigenfunctions  $f_1$  and  $f_2$ . Let  $a_1 = a_2 = a$  be the corresponding Eigenvalue, i.e.

$$\begin{array}{l}
A|f_1\rangle = a|f_1\rangle \\
A|f_2\rangle = a|f_2\rangle
\end{array}$$
(1.28)

We find:

$$A(x|f_1\rangle + y|f_2\rangle) = xa|f_1\rangle + ya|f_2\rangle = a(x|f_1\rangle + y|f_2\rangle) \qquad (1.29)$$

Thus degenerated Eigenfunctions form a sub vector space. This sub space is perpendicular to all other Eigenvectors. The orthonormalization procedure of Schmidt allows to find a set of orthogonal vectors of length 1 in this subspace.

### Orthonormal base of vectors

The system of Eigenvectors for every Hermitian matrix can thus be transformed to a set of orthonormal vectors  $e_i$ , with represent a basis in the vector space:

$$\langle e_i | e_j \rangle = \delta_{i,j} \qquad . \tag{1.30}$$

Each vector can be written as

$$\langle a| = \sum_{i} \langle a|e_i \rangle \langle e_i| \qquad . \tag{1.31}$$

which is called the Closure-relation. The  $a_i = \langle a | e_i \rangle$  are called the components of the vector for the basis  $e_i$ . In component representation the vector is just written as  $\langle a | = (a_1, a_2, a_3, ..., a_n)$ .

REMARK: Remember the Bra-, Ket- representation of vectors; for complex vectors the components have to be chosen complex conjugated when changing from Bra- to Ket- representation or vice versa.