

1.3 The linear Hermitian operator

A linear operator A is called Hermitian, if:

$$\langle x|Ay\rangle = \langle Ax|y\rangle = \langle x|A|y\rangle \quad (\text{Bra Ket}) \quad (1.11)$$

The third notation is used to point out the symmetry of the first equality.

Examples:

Hermitian matrices:

Applying the above definition to a matrix, we find:

$$|Ab\rangle_i = \sum_j A_{i,j} b_j \quad \text{and} \quad |Aa\rangle_i = \sum_j A_{i,j} a_j \quad (1.12)$$

With

$$\langle Aa|_i = \sum_j A_{i,j}^* a_j^* \quad (1.13)$$

follows

$$\langle a|Ab\rangle = \sum_{i,j} a_i^* A_{i,j} b_j \quad \text{and} \quad \langle Aa|b\rangle = \sum_{i,j} a_j^* A_{i,j}^* b_j \quad (1.14)$$

For Hermitian matrices we find according to Eq. (1.14):

$$A_{i,j} = A_{j,i}^* \quad (1.15)$$

Multiplication with x

In this case

$$\langle f|Ag\rangle = \langle Af|g\rangle = \langle f|A|g\rangle \quad (1.16)$$

is written as

$$\int_{-\infty}^{+\infty} f^*(x) x g(x) dx = \int_{-\infty}^{+\infty} x^* f^*(x) g(x) dx \quad (1.17)$$

Since x is a real value, the multiplication with x is a Hermitian operator.

The differential operator

As proofed by the following calculation, the differential operator is not Hermitian. We thus choose the correct operator

$$Af = i \frac{d}{dx} f \quad i: \text{imaginary unit} \quad (1.18)$$

We find:

$$\begin{aligned} \langle f|Ag\rangle &= \\ \int_{-\infty}^{+\infty} f^*(x) i \frac{dg}{dx}(x) dx &= i f^*(x) g(x) \Big|_{-\infty}^{+\infty} - i \int_{-\infty}^{+\infty} \frac{df^*}{dx}(x) g(x) dx \\ &= \int_{-\infty}^{+\infty} i^* \frac{df^*}{dx}(x) g(x) dx \\ &= \langle Af|g\rangle \end{aligned} \quad (1.19)$$

The partial integration gives a "boundary term". This term is zero, because f and g must be square integrable and thus are zero for large and "small" x -values.

The i leading the differential operator compensates for the minus sign which occurs in the second term after partial integration.