

2.7 Matrices

Definition 19

$$\tilde{A} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1N} \\ a_{21} & a_{22} & \cdots & a_{2N} \\ \vdots & & \ddots & \vdots \\ a_{M1} & a_{M2} & \cdots & a_{MN} \end{pmatrix} = (a_{jk}) \quad \begin{matrix} j = 1, \dots, M \\ k = 1, \dots, N \end{matrix} \quad \text{with } a_{jk} \in \mathbb{R} \text{ or } \mathbb{C}$$

\tilde{A} is called a $M \times N$ matrix, M rows or lines, N columns. i.e. vectors are matrices!

The fact that a matrix according to the definition 13 acts as a linear transformation between vectors will be needed later.

Definition 20

- Sum \oplus of two $M \times N$ matrices \tilde{A} and \tilde{B}
 $\tilde{A} + \tilde{B} = \tilde{C} : a_{jk} + b_{jk} = c_{jk}$
 zero element: $\tilde{A} = 0 \Rightarrow a_{jk} = 0$

$$\tilde{A} = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix} = \tilde{0}, \text{ of course: } \tilde{A} + \tilde{B} = \tilde{B} + \tilde{A}$$

- Scalar multiplication \otimes : $\alpha \in \mathbb{R}$ or \mathbb{C}

$$\alpha \tilde{A} = \begin{pmatrix} \alpha a_{11} & \alpha a_{12} & \cdots & \alpha a_{1N} \\ \alpha a_{21} & \alpha a_{22} & \cdots & \alpha a_{2N} \\ \vdots & & \ddots & \vdots \\ \alpha a_{M1} & \alpha a_{M2} & \cdots & \alpha a_{MN} \end{pmatrix} = (\alpha a_{jk})$$

Trivial: $\tilde{A} = \tilde{B}$ means: $a_{jk} = b_{jk}$ for all $j = 1, \dots, M$ and $k = 1, \dots, N$.
 If a_{jk} are complex numbers $a_{jk} = x_{jk} + iy_{jk}$ then simply

$$\begin{aligned} \tilde{A} &= \tilde{X} + i\tilde{Y} \quad \text{where } \tilde{X} = (x_{jk}), \tilde{Y} = (y_{jk}) \\ \overline{\tilde{A}} &= \tilde{X} - i\tilde{Y} \quad \text{complex conjugated matrix with respect to } \tilde{A} \end{aligned}$$

$M \cdot N$ base matrices $\begin{pmatrix} 1 & 0 & 0 & \cdots \\ 0 & 0 & 0 & \cdots \\ \dots & & \ddots & \dots \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 & \cdots \\ 0 & & \cdots & \dots \\ \dots & & \dots & \dots \end{pmatrix}, \text{ etc.}$

(not important here, but:) \Rightarrow Matrices form an $M \cdot N$ dimensional vector space.

Definition 21 transposed matrix

$$\tilde{A} = \begin{matrix} M \times N \text{ matrix} \\ \underbrace{(a_{jk})}_{j=1, \dots, M} \\ k=1, \dots, N \end{matrix} \Rightarrow \tilde{A}^\top = \begin{matrix} N \times M \text{ matrix} \\ \underbrace{(a_{kj})}_{k=1, \dots, N} \\ j=1, \dots, M \end{matrix}$$

adjointed matrix:

$$a_{jk} \in \mathbb{C} \quad \tilde{A} = (a_{jk}) \Rightarrow \tilde{A}^+ = (\overline{\tilde{A}})^\top = (\overline{a_{kj}}) = (\overline{\tilde{A}^\top})$$

the "bar" stands for the complex conjugated:

$$z = a + ib = re^{i\varphi}, \quad \bar{z} = a - ib = re^{-i\varphi}$$

Examples:

$$\tilde{A} = \begin{pmatrix} 1 & 2 & i \\ 3 & 1+i & 0 \\ 0 & 0 & 2 \end{pmatrix} \Rightarrow \tilde{A}^\top = \begin{pmatrix} 1 & 3 & 0 \\ 2 & 1+i & 0 \\ i & 0 & 2 \end{pmatrix} \quad \tilde{A}^+ = \begin{pmatrix} 1 & 3 & 0 \\ 2 & 1-i & 0 \\ -i & 0 & 2 \end{pmatrix}$$

$$\tilde{A} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \Rightarrow \tilde{A}^\top = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}, (\tilde{A} + \tilde{B})^\top = \tilde{A}^\top + \tilde{B}^\top, (\tilde{A}^\top)^\top = \tilde{A}$$

most important: quadratic matrices, i.e. $M = N$

$$\tilde{A} = (a_{jk})_{j, k = 1, \dots, N} = \underbrace{\begin{pmatrix} a_{11} & \cdots & a_{1N} \\ \vdots & \ddots & \vdots \\ a_{N1} & \cdots & a_{NN} \end{pmatrix}}_{\substack{\text{main diagonal elements} \\ a_{jk} \text{ with } j = k}}$$

Definition 22 trace of a quadratic matrix: $tr(\tilde{A}) = \sum_{j=1}^N a_{jj} = a_{11} + a_{22} + \dots + a_{NN}$

trivial: $tr(\tilde{A}) = tr(\tilde{A}^\top)$