4. Magnetic Materials

4.1 Definitions and General Relations

4.1.1 Fields, Fluxes and Permeability

There are [many analogies](http://www.tf.uni-kiel.de/matwis/amat/elmat_en/kap_4/basics/b4_1_1.html) between dielectric and magnetic phenomena; the big difference being that (so far) there are *no magnetic "point charges"*, so-called magnetic monopoles, but only *magnetic dipoles*. The first basic relation that we need is the relation between the magnetic flux density *B* and the magnetic field strength *H in vacuum*. It comes straight from the [Maxwell equations:](http://www.tf.uni-kiel.de/matwis/amat/semi_en/kap_2/basics/b2_2_2.html#maxwell equations) $B = \mu_0 \cdot H$ The symbols are: *B* = **magnetic flux density** or **magnetic induction**, **µo** = **magnetic permeability of the vacuum = 4π · 10–7 Vs/Am = 1,26 · 10–6 Vs/Am** \cdot *H* = magnetic field strength . The [units of the magnetic field](http://www.tf.uni-kiel.de/matwis/amat/mw1_ge/kap_2/basics/b2_1_13.html#_8) *H* and so on are \cdot $[H] = A/m$ • $[B] = Vs/m^2$, with $1Vs/m^2 = 1$ **Tesla.** *B* and *H* are vectors, of course. **103/4π A/m** used to be called **1 Oersted**, and **1 Tesla** equales **104 Gauss** in the old system. Why the eminent mathematician and scientist *Gauss* was dropped in favor of the somewhat shady figure *Tesla* remains a mystery. If a material is present, the relation between magnetic field strength and magnetic flux density becomes *B* **= µo · µr ·** *H* with μ_r = **relative permeability of the material** in [complete analogy](http://www.tf.uni-kiel.de/matwis/amat/elmat_en/kap_3/backbone/r3_1_1.html) to the *electrical flux density* and the *dielectric constant*. The relative permeability of the material **µr** is a material parameter without a dimension and thus a *pure number* (or several pure numbers if we consider it to be a *tensor* [as before\)](http://www.tf.uni-kiel.de/matwis/amat/elmat_en/kap_3/backbone/r3_1_1.html#_14). It is the material property we are after. [Again](http://www.tf.uni-kiel.de/matwis/amat/elmat_en/kap_3/backbone/r3_1_1.html#_12) , it is useful and conventional to split *B* into the *flux density in the vacuum* plus the *part of the material* according to $B = \mu_0 \cdot H + J$ With **J** = **magnetic** polarization in analogy to the dielectric case. As a new thing, we now we define the **magnetization** *M* of the material as *M* **=** *J* **µo** That is only to avoid some labor with writing. This gives us $B = \mu_0 \cdot (H + M)$ Using the [independent definition](#page-0-0) of *B* finally yields

 $M = (u_r - 1) \cdot H$ $M := \chi_{\text{maq}} \cdot H$

With *χmag* **= (µr – 1) = magnetic susceptibility**.

It is really straight along the way we looked at dielectric behavior; for a *direct comparison* use the link

The magnetic susceptibility **χmag** is the *prime material parameter* we are after; it describes the response of a material to a magnetic field in exactly the same way as the [dielectric susceptibility](http://www.tf.uni-kiel.de/matwis/amat/elmat_en/kap_3/backbone/r3_1_1.html#_9) **χdielectr**. We even chose the same abbreviation and will drop the suffix most of the time, believing in your intellectual power to keep the two apart.

Of course, the four *vectors H*, *B*, *J*, *M* are all parallel in isotropic homogeneous media (i.e. in amorphous materials and poly-crystals).

In anisotropic materials the situation is more complicated; **χ** and **µr** then must be seen as tensors.

We are left with the question of the *origin of the magnetic susceptibility*. There are no **magnetic monopoles** that could be separated into magnetic dipoles as in the case of the dielectric susceptibility, there are only *magnetic dipoles* to start from.

Why there are no magnetic monopoles (at least none have been discovered so far despite extensive search) is one of the tougher questions that you can ask a physicist; the ultimate answer seems not yet to be in. So just take it as a fact of life.

In the next paragraph we will give some thought to the the origin of magnetic dipoles.