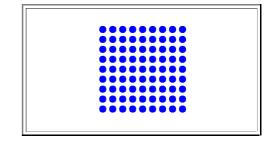
5.1.3 Essentials to Chapter 5.1: Dislocations - Basics

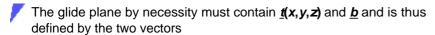
Plastic deformation of crystals=movement of dislocations through the crystal.

- The distortion necessary to deform a crystal is localized in a 1-dimensional defect=dislocation that moves through the crystal under the influence of (external shear) forces.
- "Discovery" of dislocations as source of plastic deformation=answer to one of the biggest and oldest scientific puzzles in 1934 (Taylor, Orowan and Polyani). No Noble prize!
- Movement of dislocations produce steps of atomic size characterized by a vector called "Burgers vector".
- Movement of dislocations occurs in a plane (=glide plane) and shifts the upper part of the crystal with respect to the lower part.

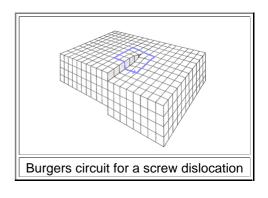


Dislocations are characterized by

- **1.** Their Burgers vector <u>b</u>=
 - vector describing the step obtained after a dislocation passed through the crystal.
 - · Vector obtained by a Burgers circuit around a dislocation.
 - Translation vector in the Volterra procedure.
 - All definitions of <u>b</u> give identical results for a given dislocations; but watch out for sign conventions!
 - By definition, <u>b</u> is always a translation vector <u>T</u> of the lattice.
 - For energetic reasons <u>b</u> is usually the shortest translation vector of the lattice; e.g. <u>b=a/2</u> <110> for the fcc lattice.
- **2.** Their line vector $\underline{t}(x,y,z)$ describing the direction of the dislocation line in the lattice
 - <u>f(x,y,z)</u> is an arbitrary (unit) vector in principle but often a prominent lattice direction in reality
 - While the dislocation can be curved in any way, it tends to be straight (=shortest possible distance) for energetic reasons.

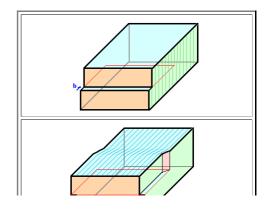


- The angle α between <u>t(x,y,z)</u> and <u>b</u> determines the character or kind of dislocation:
- Note that any plane containing <u>t</u> is a glide plane for a screw dislocation.
- Dislocations have a large line energy **E**_{dis} per length and therefore are never thermal equilibrium defects
- The formal Volterra definition of dislocations is very useful and extendable to more complex kinds of dislocations
 - Cut into the *lattice* with a fictitious "Volterra" knife (make a plane cut to keep it easy), The cut line is a closed loop by necessity. The part of the cut line inside the crystal identifies the dislocation line.
 - Move the part of the lattice above (or below attention, signs change!!) the cut plane by an arbitrary lattice translation vector=Burgers vector of the dislocation. Add or remove lattice points as necessary (=remove or fill in atoms in the crystal going with the lattice).



- α=90 °: Edge dislocation.
- α**=0** °: Screw dislocation.
- α=60 °: "Sixty degree" dislocation.
- α=arbitrary : "Mixed" dislocation.

*E*_{dis} ≈ 5 eV/|<u>b</u>|



- Mend the lattice (or crystal) by "welding the upper part to the lower one. There will be a perfect fit by definition everywhere except along the dislocation line.
- Make the best arrangement of the atoms along the dislocation line by minimizing their energy (make best possible bonds).
- You now have formed a dislocation.
 - The procedure is "easily" extended to dislocations in n-dim. lattices, to (special) dislocations with a Burgers vector not defined as translation vector of the lattice and to lattices more complex than a simple crystal lattice.
- b 1

- Direct consequences are:
 - A dislocation cannot just end in the interior of a crystal
 - There is a "knot rule" for dislocation knots:

S<u>b</u>=0

provided the signs of the line vectors follow a convention (all pointing to or away from the knot)

 There can be all kinds of dislocation loops (just confine your fictitious cut to the lattice interior!)

